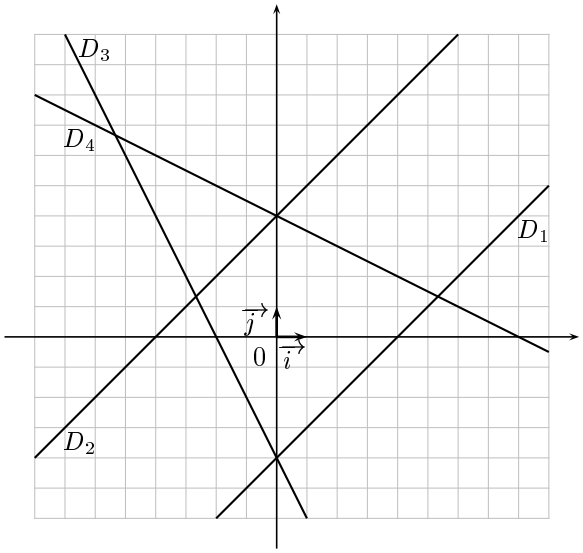
D_3
D_4
D_1
$\vec{j}$
0
$\vec{i}$
D_2